

Depth
Onboard
Processing



Win/Linux OpenNI2/ROS

SDK







Measurement Range 1.25~4.3m Sync & Alignment RGB-D

3D Accuracy
Submillimeter

Overview

Percipio's 3D smart camera uses innovative active stereo vision technology with core patents to obtain more depth details and more robust environmental adaptability than traditional binocular vision.

PM806-E1 combines the structured light with the mature RGB sensor technology to provide real-time RGB and depth images.

With reliable measurement results and the carbon-fiber body, PM806-E1 is an ideal solution for robotics, logistics, inspection and other applications.

Advantages

PM806-E1 includes two infrared (IR) sensors, one RGB sensor and several structured-light projectors. Comparing to traditional binocular cameras, PM806-E1 provides:

- More depth details
- + More robust to ambient light interference

Industrial Sensor

PM806-E1 is splash, water, and dust resistant and has been tested under controlled laboratory conditions with a rating of IP54 under IEC standard 60529.

Trigger Mode

PM806-E1 supports the software trigger and hardware trigger. The customers can synchronize multi-cameras to capture images with the hardware trigger.

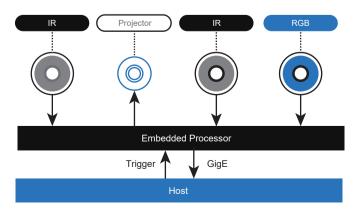
High Accuracy

With the innovative multi-laser projecting system, PM806-E1 provides high measurement accuracy in its large working range and wide FOV.

Note:

All cameras have been calibrated with intrinsic parameters before delivery. If you need to calibrate multiple cameras with extrinsic parameters, please contact Percipio technical support.

Principle



Structured-light Projector

Project the structured light to objects for assisting the active stereo system to calculate depth data.

Infrared Sensor

Receive the structured light reflected from the objects surface.

RGB Sensor

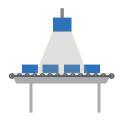
Capture RGB images.

Embedded Processor

Process infrared and RGB images:

- Calculate depth data and achieve alignment and synchronization with RGB images.
- Upload data through Gigabit Ethernet (GigE).
- Receive trigger signal from the host or the hardware trigger source.

Applications











Integrity Check

3D Content Generation

Palletizing / De-palletizing

Volume Measurement

Industrial Sorting

Features

Dimension&Weight		Interface	
LxHxW	538.4 mm × 85.5 mm × 89.6 mm	Power&Trigger	8-pin aviation plug
Weight	2.2 kg	Ethernet	M12 X-Coding
Measurement		Electronics	
Measurement Range (mm)	1250 ~ 4300	Supply Voltage	DC 24 V 3A;
FOV (H/V)	64°/49°		IEEE802.3at POE
		Power (Idle Mode)	6.0 W
Z Accuracy (mm)	2.76mm@2500mm	Power (Continuous Mode)	16.0 W
X/Y Accuracy (mm)	5.72mm@2500mm	Power (Trigger Mode)	14.0 W
Software		Ambient Data	
os	Linux/Windows/Android/ROS	Operating Temperature	0°C∼45°C
Development Platform	Percipio Camport SDK	Storage Temperature	-10℃~55℃
API	C/C++、C#、Python、Java	Enclosure Rating	IP54
Performance			
Depth	1 fps @ 1280×960	RGB	4 fps @ 2560×1920
	1 fps @ 640×480		16 fps @ 1280×960
	1 fps @ 320×240		30 fps @ 640×480
RGB-D Sync&Alignment		\checkmark	
Output Data		Point cloud, depth, infrared and RGB images	
Note:			



The specs and dimension may change without notice.

For purchase or business cooperation, please email us:

For technical support, please email us:

For more information about Percipio 3D cameras, please visit:

For online documentation, please visit:

info@percipio.xyz

support@percipio.xyz

www.percipio.xyz

doc.percipio.xyz/cam/latest/